

I2C Input –Output Port Expander MCP23017

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Introduction:

The IO Expander Board is based on the Microchip MCP23017 Expander Chip. This high-performance IC, allows connection to a range of High-Speed I²C buses, including the standard 100kHz bus, as well as the newer 400kHz and 1.7MHz bus standards.

Features:

- Includes Microchip MCP23017 16-Bit I/O Expander Chip
- Board can be controlled with High-Speed I²C Connection.
- Standard Male Headers for Board Interfacing.
- Suitable for 5V Systems.
- Three hardware address pins to allow up to eight devices on the bus

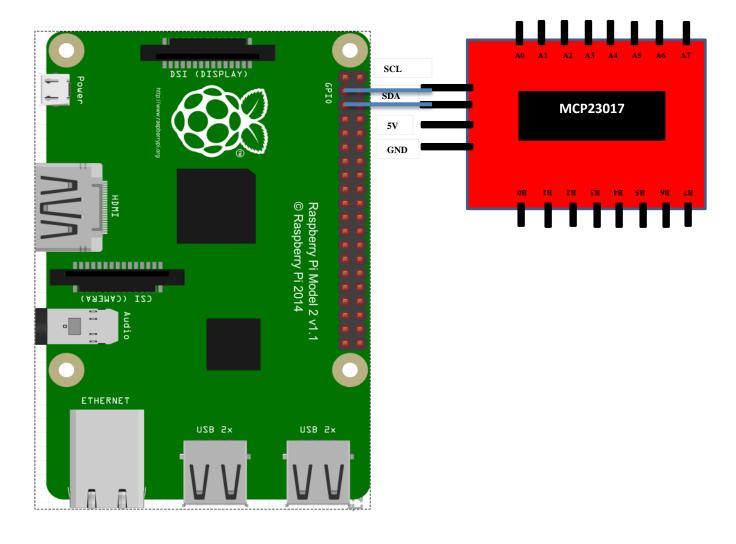
MCP23017 Features:

- 16-bit remote bidirectional I/O port I/O pins default to input
- High-speed I2CTM interface (MCP23017) 100 kHz 400 kHz 1.7 MHz
- Three hardware address pins to allow up to eight devices on the bus
- Configurable interrupt output pins Configurable as active-high, active-low or open-drain
- INTA and INTB can be configured to operate independently or together
- Configurable interrupt source Interrupt-on-change from configured register defaults or pin changes
- Polarity Inversion register to configure the polarity of the input port data
- External Reset input
- Low standby current: 1 μA (max.)
- Operating voltage: 1.8V to 5.5V @ -40°C to +85°C 2.7V to 5.5V @ -40°C to +85°C 4.5V to 5.5V @ -40°C to +125°C

Package Contains:

IO Expander Board MCP23017 IC+ Male Burgestick

Internal Block connections:



Working Steps:

Steps 1:

First check whether raspberry is detecting I2C device by typing following command.

Sudo i2cdetect -y 1

Step 2:

Configure a port which u want to use by using following command.

Sudo i2cset -y 1 0x20 0x00 0x80



Step 3:

Turn on LED connected to pin7 by using following command.

Sudo i2cset -y 1 0x20 0x14 0x01

```
pi@raspberrypi ~/testing $ sudo i2cset -y 1 0x20 0x00 0x80
pi@raspberrypi ~/testing $ sudo i2cset -y 1 0x20 0x14 0x01

^
```

Turn off led by following command.

Sudo i2cset -y 1 0x20 0x14 0x00

Python script to count binary 000 to 111 using IO-Expander:

Step 1: open nano editor using command python filename.py

Step 2: write a following code in the nano editor as shown below.

import smbus

import time

#bus = smbus.SMBus(0) # Rev 1 Pi uses 0

bus = smbus.SMBus(1) # Rev 2 Pi uses 1

DEVICE = 0x20 # Device address (A0-A2)

IODIRA = 0x00 # Pin direction register

OLATA = 0x14 # Register for outputs

GPIOA = 0x12 # Register for inputs

```
# Set all GPA pins as outputs by setting

# all bits of IODIRA register to 0

bus.write_byte_data(DEVICE,IODIRA,0x00)

# Set output all 7 output bits to 0

bus.write_byte_data(DEVICE,OLATA,0)

for MyData in range(1,8):

# Count from 1 to 8 which in binary will count

# from 001 to 111

bus.write_byte_data(DEVICE,OLATA,MyData)

print MyData

time.sleep(1)

# Set all bits to zero

bus.write_byte_data(DEVICE,OLATA,0)
```

```
pi@raspberrypi: ~/testing
  GNU nano 2.2.6
                                                           File: io expander.py
import smbus
import time
#bus = smbus.SMBus(0) # Rev 1 Pi uses 0
bus = smbus.SMBus(1) # Rev 2 Pi uses 1
DEVICE = 0x20 \# Device address (A0-A2)
IODIRA = 0x00 # Pin direction register
OLATA = 0x14 # Register for outputs
GPIOA = 0x12 # Register for inputs
# Set all GPA pins as outputs by setting
# all bits of IODIRA register to 0
bus.write byte data(DEVICE,IODIRA,0x00)
# Set output all 7 output bits to 0
bus.write_byte_data(DEVICE,OLATA,0)
for MyData in range(1,8):
  # Count from 1 to 8 which in binary will count
  # from 001 to 111
  bus.write_byte_data(DEVICE,OLATA,MyData)
  print MyData
  time.sleep(1)
# Set all bits to zero
bus.write_byte_data(DEVICE,OLATA,0)
```

Step 3:

Run above code by typing sudo python filename.py